



## <u>Lecture 1</u>

#### ME 276

Spring 2017-2018

Dr./ Ahmed Mohamed Nagib Elmekawy

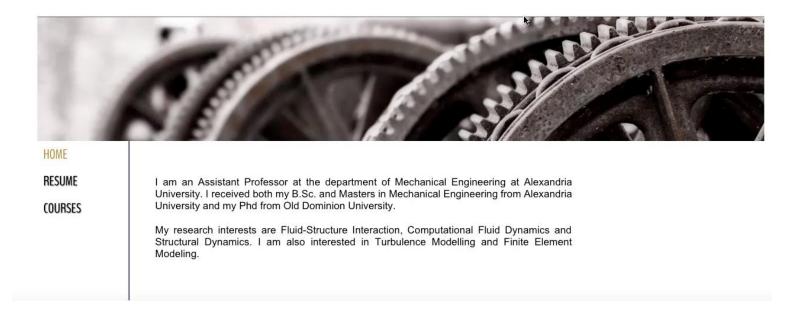
#### **Course Materials**

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# COURSE OUTLINE

## **COURSE OUTLINE**

- Fundamentals
  - Introduction Mechanical Engineering Design
  - Load Analysis
  - o Materials
  - Stresses and Strains
  - Theories of Failure
- Applications
  - o Bolt Design
  - Power Screw Design
  - Shaft Design



# Fundamentals

## Introduction - Mechanical Engineering Design

## Introduction - Mechanical Engineering Design

- Phases and Interactions of the Design Process
- Design Considerations.
- Design Tools and Resources.
- Standard and Codes.
- System of Units.
- Economics.
- Safety.

This course is concerned with the design and analysis of machine and structural components. Since these are loadcarrying members, an analysis of loads is of fundamental importance. A sophisticated stress or deflection analysis is of little value if it is based on incorrect loads. A mechanical component cannot be satisfactory unless its design is based on realistic operating loads.

Sometimes the service or operating loads can be readily determined, as are those on some engines, compressors, and electric generators that operate at known torques and speeds. Often the loads are difficult to determine, as are those on automotive chassis components (which depend on road surfaces and driving practices) or on the structure of an airplane (which depends on air turbulence and pilot decisions).

Sometimes experimental methods are used to obtain a statistical definition of applied loads. In other instances engineers use records of service failures together with analyses of strength in order to infer reasonable estimates of loads encountered in service.

The determination of appropriate loads is often a difficult and challenging initial step in the design of a machine or structural component.

• Equilibrium equation

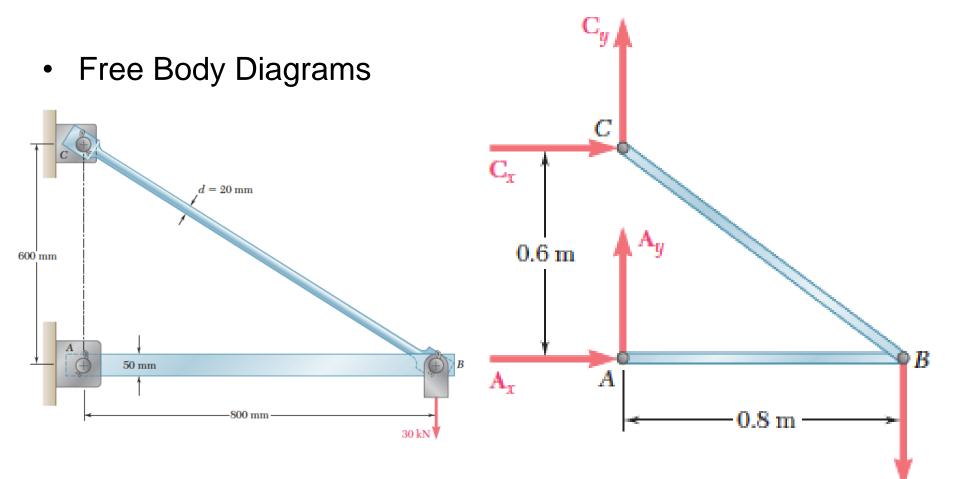
For a nonaccelerating body

$$\Sigma F = 0$$
 and  $\Sigma M = 0$ 

For a accelerating body

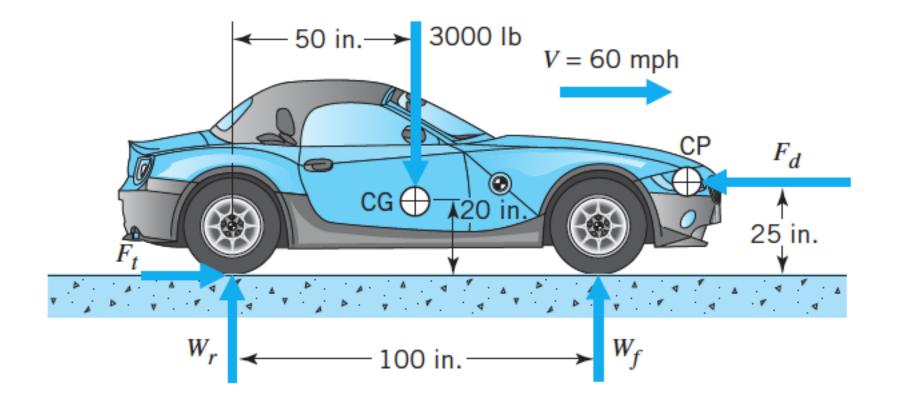
$$\Sigma F = ma$$
 and  $\Sigma M = I\alpha$ 



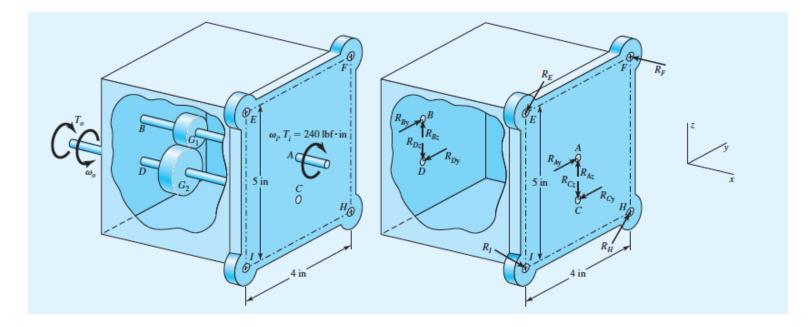


30 kN

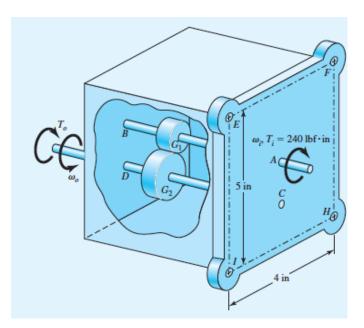
• Free Body Diagrams

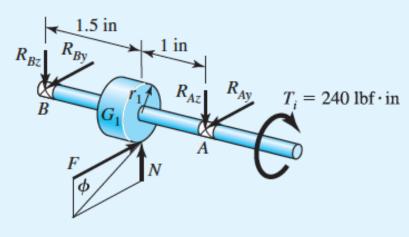


• Free Body Diagrams

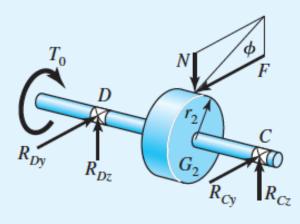


• Free Body Diagrams



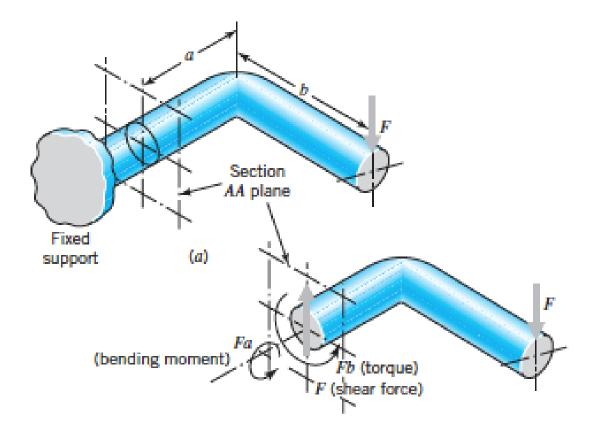


(c) Input shaft



(d) Output shaft

• Determination of internal Loads





#### **Materials**

#### **Material Selection**

Family	Classes	Short Name
Metals (the metals and alloys of engineering)	Aluminum alloys Copper alloys Lead alloys Magnesium alloys Nickel alloys Carbon steels Stainless steels Tin alloys Titanium alloys Tungsten alloys Lead alloys	Al alloys Cu alloys Lead alloys Mg alloys Ni alloys Steels Stainless steels Tin alloys Ti alloys W alloys W alloys Pb alloys
	Zinc alloys	Zn alloys
Ceramics Technical ceramics (fine ceramics capable of load-bearing application) Nontechnical ceramics (porous ceramics of construction)	Alumina Aluminum nitride Boron carbide Silicon carbide Silicon nitride Tungsten carbide Brick Concrete Stone	Al <sub>2</sub> O <sub>3</sub> AlN B <sub>4</sub> C SiC Si <sub>3</sub> N <sub>4</sub> WC Brick Concrete Stone
Glasses	Soda-lime glass Borosilicate glass Silica glass Glass ceramic	Soda-lime glass Borosilicate glass Silica glass Glass ceramic
Polymers (the thermoplastics and thermosets of engineering)	Acrylonitrile butadiene styrene Cellulose polymers Ionomers Epoxies Phenolics Polyamides (nylons) Polycarbonate	ABS CA Ionomers Epoxy Phenolics PA PC

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#### **Materials**

#### **Material Selection**

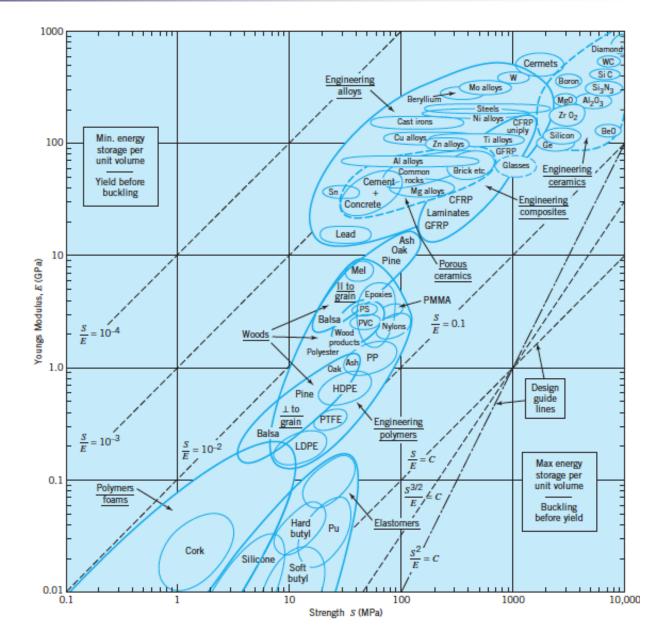
Family	Classes	Short Name
Polymers (continued)	Polyesters Polyetheretherkeytone Polyethylene Polyethylene terephalate Polymethylmethacrylate Polyoxymethylene(Acetal)	Polyester PEEK PE PET or PETE PMMA POM
	Polypropylene Polystyrene Polytetrafluorethylene Polyvinylchloride	PP PS PTFE PVC
Elastomers (engineering rubbers, natural and synthetic)	Butyl rubber EVA Isoprene Natural rubber Polychloroprene (Neoprene) Polyurethane Silicon elastomers	Butyl rubber EVA Isoprene Natural rubber Neoprene PU Silicones
Hybrids Composites	Carbon-fiber reinforced polymers Glass-fiber reinforced polymers SiC reinforced aluminum	CFRP GFRP Al-SiC
Foams	Flexible polymer foams Rigid polymer foams	Flexible foams Rigid foams
Natural materials	Cork Bamboo Wood	Cork Bamboo Wood

From M. F. Ashby, *Materials Selection in Mechanical Design*, 3rd ed., Elsevier Butterworth-Heinemann, Oxford, 2005. Table 4–1, pp. 49–50.

#### <u>Materials</u>

Material Selection

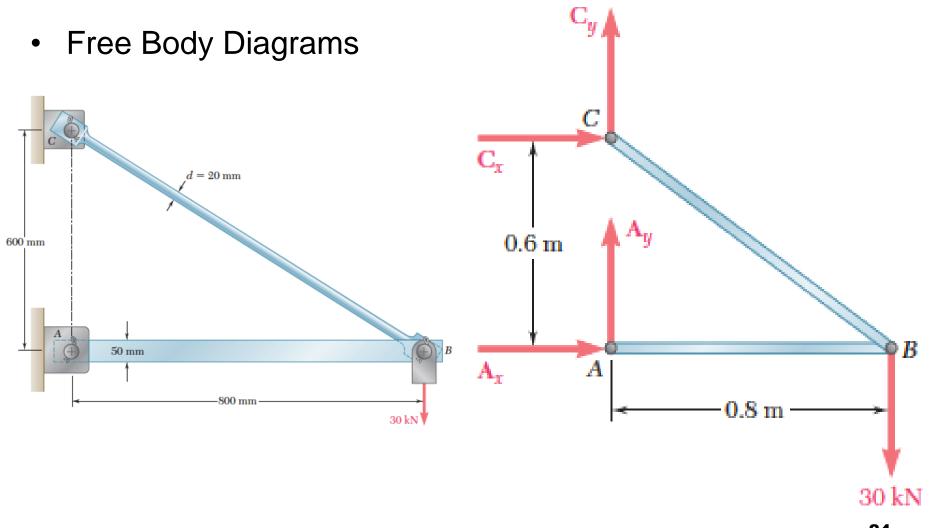
Strength



#### **Materials**

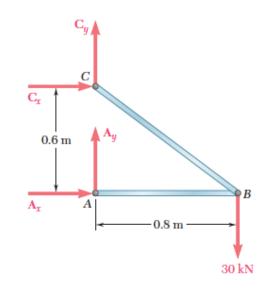
**Material Selection Factors** 

- 1. Availability
- 2. Cost
- 3. Material properties—mechanical, physical, chemical, dimensional
- 4. Manufacturing processes—machining, formability, joinability, finishing and coatings



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• Free Body Diagrams



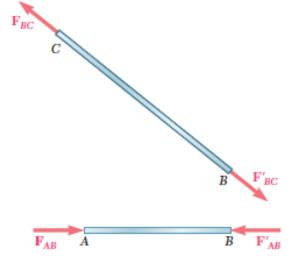
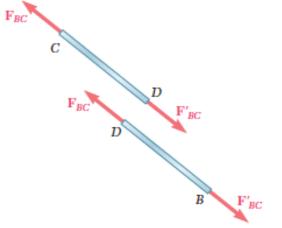
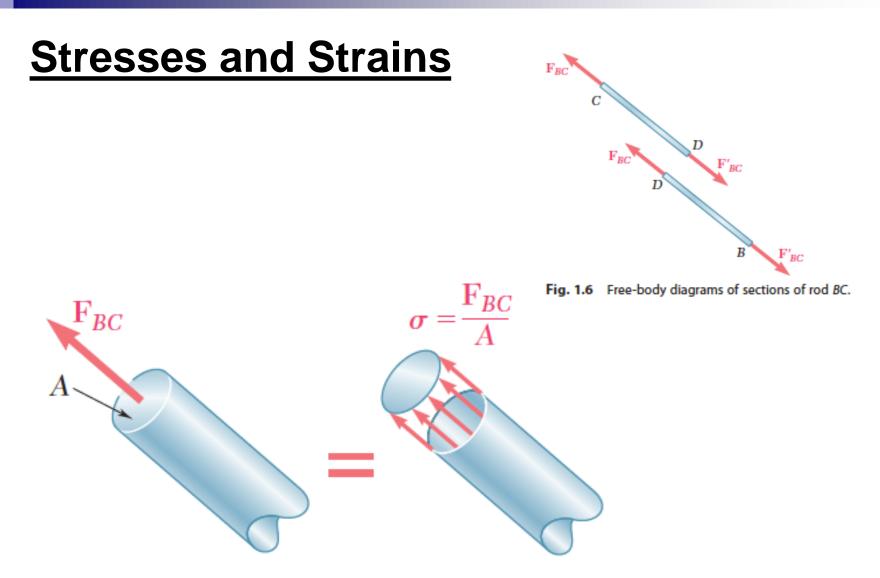


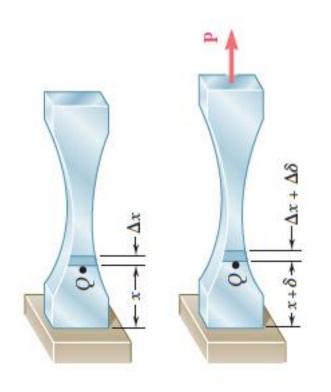
Fig. 1.5 Free-body diagrams of two-force members *AB* and *BC*.







**Fig. 1.7** Axial force represents the resultant of distributed elementary forces.



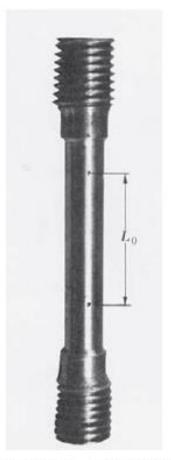
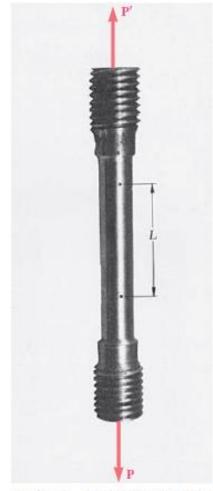


Photo 2.1 Typical tensile-test specimen. Undeformed gage length is L<sub>0</sub>.



Photo 2.2 Universal test machine used to test tensile specimens.



**Photo 2.3** Elongated tensile test specimen having load P and deformed length  $L > L_0$ .

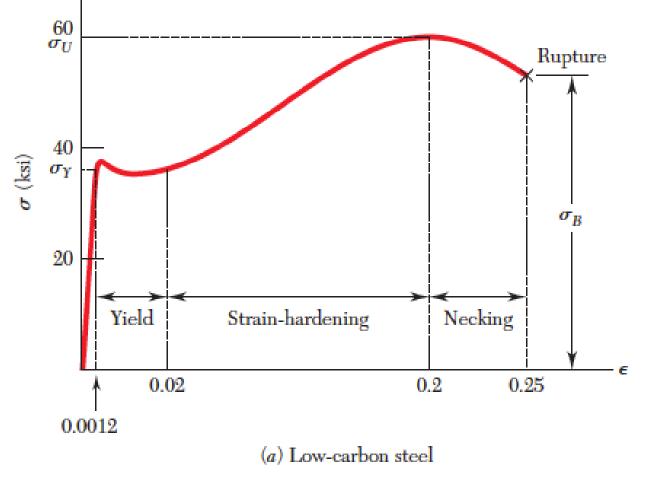
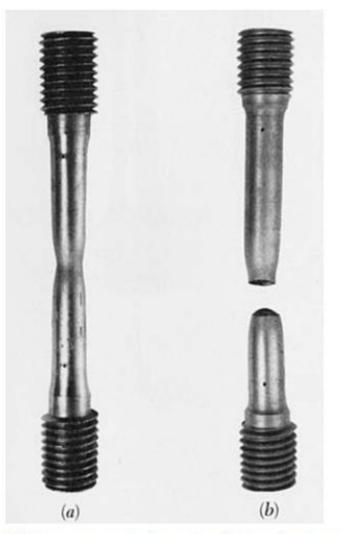
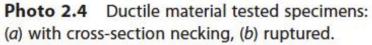


Fig. 2.6 Stress-strain diagrams of two typical ductile materials.

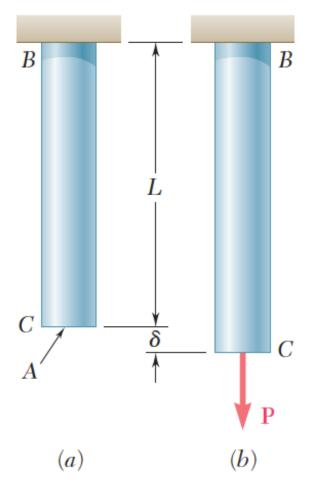








#### 1. Axial Load



**Fig. 2.1** Undeformed and deformed axially-loaded rod.

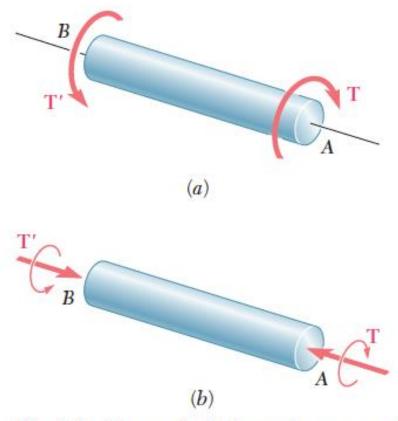


#### 1. Axial Load





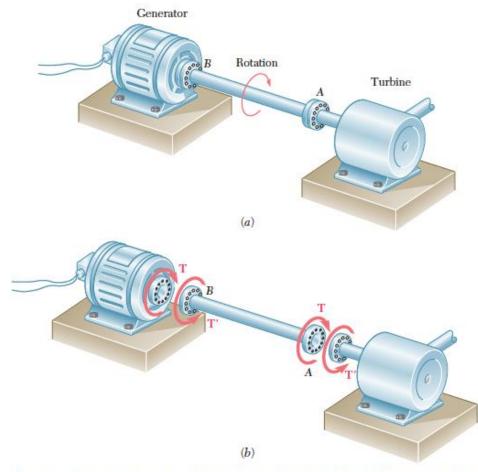
#### 2. Torsion Load



**Fig. 3.1** Two equivalent ways to represent a torque in a free-body diagram.



#### 2. Torsion Load

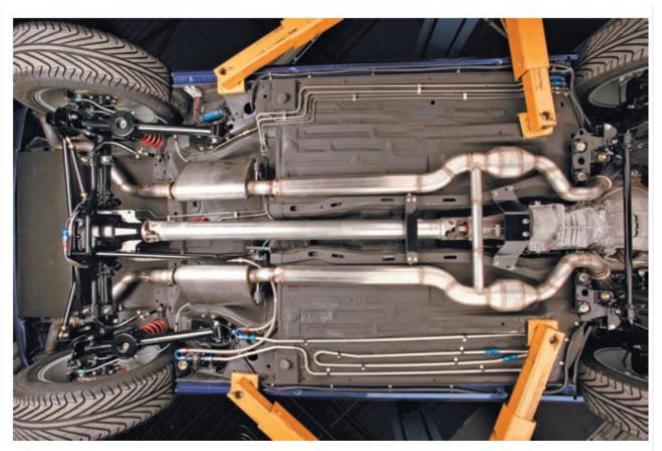


**Fig. 3.2** (a) A generator receives power at a constant number of revolutions per minute from a turbine through shaft *AB*. (b) Free-body diagram of shaft *AB* along with the driving and reacting torques on the generator and turbine, respectively.





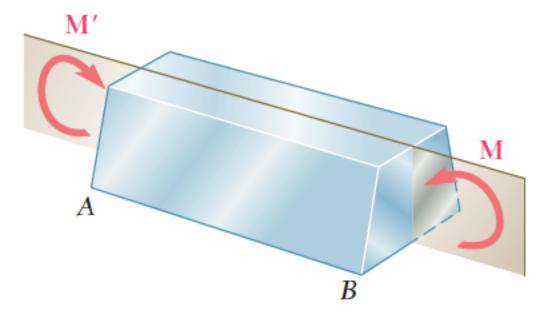
#### 2. Torsion Load

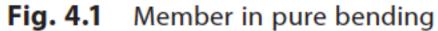


**Photo 3.1** In this automotive power train, the shaft transmits power from the engine to the rear wheels.



#### 3. Bending Load

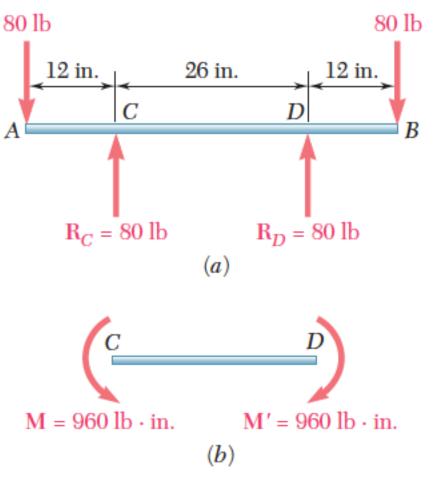




#### <u>Stresses</u>

#### 3. Bending Load





**Fig. 4.2** (*a*) Free-body diagram of the barbell pictured in the chapter opening photo and (*b*) free-body diagram of the center portion of the bar, which is in pure bending. 37



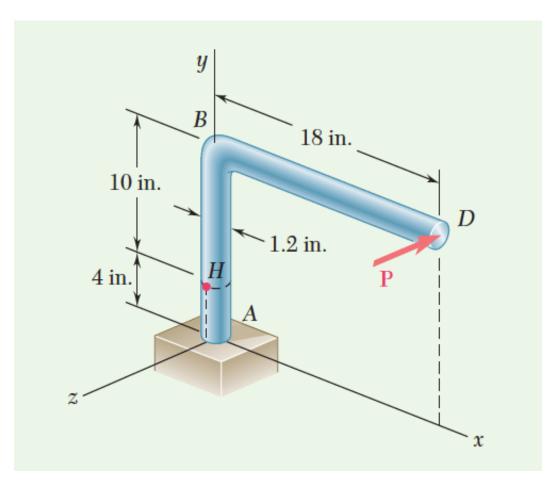
#### 3. Bending Load



**Photo 4.1** The center portion of the rear axle of the sport buggy is in pure bending.



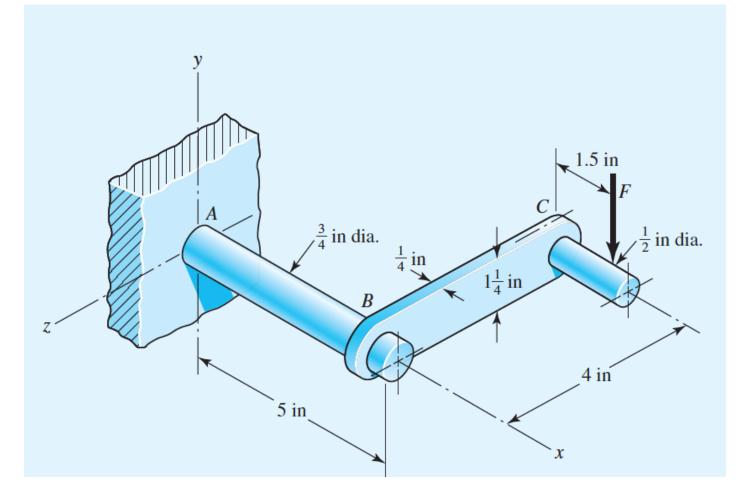
#### 4. Combined Loading





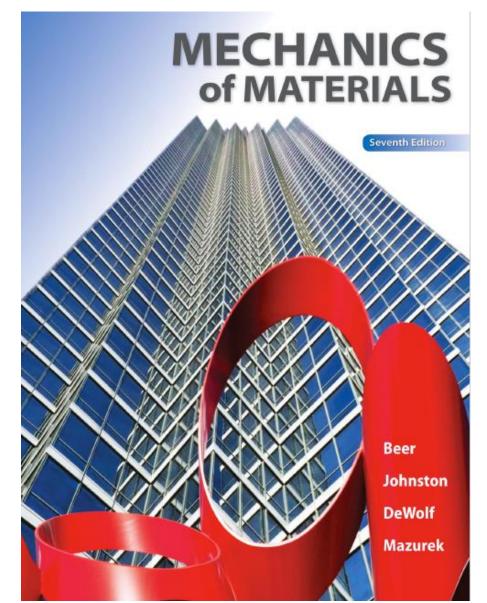


#### 4. Combined Loading





#### **References**



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